

# Program at a Glance

	Monday			Tuesday	
9:00 – 9:30				<b>Conference Welcome</b> <i>1001T</i>	
9:30 – 10:30	<b>Workshops</b> eCAS, <i>1003T</i> AMGCC'16, <i>2001T</i> QA4SASO, <i>2002T</i>	<b>Tutorial</b> Knowledge Level Models of Situations and Situation Assessment <i>2004T</i>	<b>Special Track</b> Trustworthy Open Self-Organizing Systems <i>1005T</i>	<b>Keynote Marco Dorigo</b> Collective Decision Making: The Best-of-n Problem in Robot Swarms <i>1001T</i>	
10:30 – 11:00	Coffee Break				
11:00 – 12:30	<b>Workshops</b> eCAS, <i>1003T</i> AMGCC'16, <i>2001T</i> QA4SASO, <i>2002T</i>	<b>Tutorial</b> Knowledge Level Models of Situations and Situation Assessment <i>2004T</i>	<b>Special Track</b> Trustworthy Open Self-Organizing Systems <i>1005T</i>	<b>SASO</b> Session 1: Swarm Robotics <i>1001T</i>	<b>ICCAC</b> Session 1: Scheduling and Allocation <i>1002T</i>
12:30 – 14:00	Lunch Break				
14:00 – 15:30	<b>Workshops</b> eCAS, <i>1003T</i> AMGCC'16, <i>2001T</i> QA4SASO, <i>2002T</i> DSS, <i>2003T</i>	<b>Tutorial</b> Model-based Cloudification of Critical Applications <i>2004T</i>	<b>Special Track</b> Trustworthy Open Self-Organizing Systems <i>1005T</i>	<b>SASO</b> Session 2: Agents and Learning <i>1001T</i>	<b>ICCAC</b> Session 2: Data Management <i>1002T</i>
15:30 – 16:00	Coffee Break				
16:00 – 17:30	<b>Workshops</b> eCAS, <i>1003T</i> AMGCC'16, <i>2001T</i> QA4SASO, <i>2002T</i> DSS, <i>2003T</i>	<b>Tutorial</b> Model-based Cloudification of Critical Applications <i>2004T</i>	<b>Special Track</b> Trustworthy Open Self-Organizing Systems <i>1005T</i>	<b>SASO</b> Session 3: Spatial Computing <i>1001T</i>	<b>ICCAC</b> Session 3: Storage and Small Business, and Other Short Papers <i>1002T</i> (until 18:00)
	City Tour: Meeting point in front of the Physik Hörsaalzentrum at 17:30.				
19:00 – 22:00	Welcome Reception				

# Program at a Glance

Wednesday		Thursday		Friday		
<b>Keynote Manish Gupta</b> Using Data Science and Cloud to Scale and Personalize Services <i>1001T</i>		<b>Keynote Dominik Bösl</b> Future of Robotics – Paving the Way for a Generation 'R' of Robotic Natives in the Age of Digitalization <i>1001T</i>		<b>Workshops</b> SASO <sup>^</sup> ST, <i>1003T</i> SOCO, <i>1005T</i> FMEC/ISCW, <i>2002T</i> DSPL, <i>2003T</i>	<b>Tutorial</b> Context for Adaptive Information Fusion <i>2004T</i>	<b>Special Track</b> DREAMing – Optimization and Learning of Robotic Tasks in Simulation <i>2001T</i>
Coffee Break						
<b>SASO</b> Session 4: Institutions and Organizations <i>1001T</i>	<b>ICCAC</b> Session 4: System Management <i>1002T</i>	<b>SASO</b> Session 5: Resource Management <i>1001T</i>	<b>Workshops</b> SASO <sup>^</sup> ST, <i>1003T</i> SOCO, <i>1005T</i> FMEC/ISCW, <i>2002T</i> DSPL, <i>2003T</i>	<b>Tutorial</b> Context for Adaptive Information Fusion <i>2004T</i>	<b>Special Track</b> DREAMing – Optimization and Learning of Robotic Tasks in Simulation <i>2001T</i>	
Lunch Break						
<b>Posters and Demo</b> Lightning Talks <i>1001T</i>		<b>SASO</b> Session 6: Short Papers <i>1001T</i>	<b>Doctoral Symposium</b> Invited Talk and Panel Discussion <i>1005T</i>	<b>Workshops</b> SASO <sup>^</sup> ST, <i>1003T</i> SOCO, <i>1005T</i> FMEC/ISCW, <i>2002T</i> DSPL, <i>2003T</i>	<b>Tutorial</b> Solving Soft Constraint Problems in Autonomic Systems with MiniBrass <i>2004T</i>	
Coffee Break						
<b>Posters and Demo</b> Poster Presentations <i>Foyer</i>		<b>Doctoral Symposium</b> Paper Presentations <i>1005T</i>		<b>Workshops</b> SOCO, <i>1005T</i> FMEC/ISCW, <i>2002T</i> DSPL, <i>2003T</i>	<b>Tutorial</b> Solving Soft Constraint Problems in Autonomic Systems with MiniBrass <i>2004T</i>	
		<b>SASO Conference Closing</b> <i>1001T</i>				
Conference Dinner						